NAG Fortran Library Routine Document

C06RCF

Note: before using this routine, please read the Users' Note for your implementation to check the interpretation of **bold italicised** terms and other implementation-dependent details.

1 Purpose

C06RCF computes the discrete quarter-wave Fourier sine transforms of m sequences of real data values.

2 Specification

SUBROUTINE COGRCF(DIRECT, M, N, X, WORK, IFAIL)
INTEGER M, N, IFAIL

real X(M*(N+2)), WORK(M*N+2*N+15)

CHARACTER*1 DIRECT

3 Description

Given m sequences of n real data values x_j^p , for j = 1, 2, ..., n and p = 1, 2, ..., m, this routine simultaneously calculates the quarter-wave Fourier sine transforms of all the sequences defined by

$$\hat{x}_{k}^{p} = \frac{1}{\sqrt{n}} \left(\sum_{j=1}^{n-1} x_{j}^{p} \times \sin \left(j(2k-1) \frac{\pi}{2n} \right) + \frac{1}{2} (-1)^{k-1} x_{n}^{p} \right), \quad \text{if} \quad$$

DIRECT = 'F', or its inverse

$$x_k^p = \frac{2}{\sqrt{n}} \sum_{j=1}^n \hat{x}_j^p \times \sin\left((2j-1)k\frac{\pi}{2n}\right), \quad \text{if}$$

DIRECT = 'B', for k = 1, 2, ..., n and p = 1, 2, ..., m.

(Note the scale factor $\frac{1}{\sqrt{n}}$ in this definition.)

A call of the routine with DIRECT = 'F' followed by a call with DIRECT = 'B' will restore the original data

The transform calculated by this routine can be used to solve Poisson's equation when the solution is specified at the left boundary, and the derivative of the solution is specified at the right boundary (Swarztrauber (1977)).

The routine uses a variant of the fast Fourier transform (FFT) algorithm (Brigham (1974)) known as the Stockham self-sorting algorithm, described in Temperton (1983a), together with pre- and post-processing stages described in Swarztrauber (1982). Special coding is provided for the factors 2, 3, 4 and 5.

4 References

Brigham E O (1974) The Fast Fourier Transform Prentice-Hall

Swarztrauber P N (1977) The methods of cyclic reduction, Fourier analysis and the FACR algorithm for the discrete solution of Poisson's equation on a rectangle SIAM Rev. 19 (3) 490–501

Swarztrauber P N (1982) Vectorizing the FFT's Parallel Computation (ed G Rodrique) 51-83 Academic Press

Temperton C (1983a) Fast mixed-radix real Fourier transforms J. Comput. Phys. 52 340-350

[NP3546/20A] C06RCF.1

5 Parameters

1: DIRECT – CHARACTER*1

Input

On entry: if the Forward transform as defined in Section 3 is to be computed, then DIRECT must be set equal to 'F'. If the **B**ackward transform is to be computed then DIRECT must be set equal to 'B'.

Constraint: DIRECT = 'F' or 'B'.

2: M – INTEGER Input

3: N – INTEGER Input

4: X(M*(N+2)) - real array

Input/Output

On entry: the data must be stored in X as if in a two-dimensional array of dimension (1:M, 1:N+2); each of the m sequences is stored in a **row** of the array. In other words, if the data values of the pth sequence to be transformed are denoted by x_j^p , for $j=1,2,\ldots,n$ and $p=1,2,\ldots,m$, then the first mn elements of the array X must contain the values

$$x_1^1, x_1^2, \dots, x_1^m, x_2^1, x_2^2, \dots, x_2^m, \dots, x_n^1, x_n^2, \dots, x_n^m$$

The (n+1)th and (n+2)th elements of each row x_{n+1}^p , x_{n+2}^p , for $p=1,2,\ldots,m$, are required as workspace. These 2m elements may contain arbitrary values as they are set to zero by the routine.

On exit: the m quarter-wave sine transforms stored as if in a two-dimensional array of dimension (1:M,1:N+2). Each of the m transforms is stored in a **row** of the array, overwriting the corresponding original sequence. If the n components of the pth quarter-wave sine transform are denoted by \hat{x}_k^p , for $k=1,2,\ldots,n$ and $p=1,2,\ldots,m$, then the m(n+2) elements of the array X contain the values

$$\hat{x}_1^1, \hat{x}_1^2, \dots, \hat{x}_1^m, \ \hat{x}_2^1, \hat{x}_2^2, \dots, \hat{x}_2^m, \dots, \ \hat{x}_n^1, \hat{x}_n^2, \dots, \hat{x}_n^m, 0, 0, \dots, 0 \ (2m \text{ times}).$$

5: WORK(M*N+2*N+15) - real array

Workspace

6: IFAIL – INTEGER

Input/Output

On entry: IFAIL must be set to 0, -1 or 1. Users who are unfamiliar with this parameter should refer to Chapter P01 for details.

On exit: IFAIL = 0 unless the routine detects an error (see Section 6).

For environments where it might be inappropriate to halt program execution when an error is detected, the value -1 or 1 is recommended. If the output of error messages is undesirable, then the value 1 is recommended. Otherwise, for users not familiar with this parameter the recommended value is 0. When the value -1 or 1 is used it is essential to test the value of IFAIL on exit.

6 Error Indicators and Warnings

If on entry IFAIL = 0 or -1, explanatory error messages are output on the current error message unit (as defined by X04AAF).

Errors or warnings detected by the routine:

C06RCF.2 [NP3546/20A]

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IFAIL = 1IFAIL = 2IFAIL = 3
```

IFAIL = 4

7 Accuracy

Some indication of accuracy can be obtained by performing a subsequent inverse transform and comparing the results with the original sequence (in exact arithmetic they would be identical).

8 Further Comments

The time taken by the routine is approximately proportional to $nm \times \log n$, but also depends on the factors of n. The routine is fastest if the only prime factors of n are 2, 3 and 5, and is particularly slow if n is a large prime, or has large prime factors.

9 Example

This program reads in sequences of real data values and prints their quarter-wave sine transforms as computed by C06RCF with DIRECT = 'F'. It then calls the routine again with DIRECT = 'B' and prints the results which may be compared with the original data.

9.1 Program Text

Note: the listing of the example program presented below uses **bold italicised** terms to denote precision-dependent details. Please read the Users' Note for your implementation to check the interpretation of these terms. As explained in the Essential Introduction to this manual, the results produced may not be identical for all implementations.

```
CO6RCF Example Program Text.
   Mark 19 Release. NAG Copyright 1999.
   .. Parameters ..
                     NIN, NOUT
   INTEGER
   PARAMETER
                     (NIN=5, NOUT=6)
                     MMAX, NMAX
   TNTEGER
                    (MMAX=5,NMAX=20)
   PARAMETER
   .. Local Scalars ..
   INTEGER
                    I, IFAIL, J, M, N
   .. Local Arrays ..
                    WORK (MMAX*NMAX+2*NMAX+15), X((NMAX+2)*MMAX)
   .. External Subroutines ..
   EXTERNAL
                    CO6RCF
   .. Executable Statements ..
   WRITE (NOUT,*) 'CO6RCF Example Program Results'
   Skip heading in data Ûle
  READ (NIN, *)
20 CONTINUE
   READ (NIN, \star, END=120) M, N
   IF (M.LE.MMAX .AND. N.LE.NMAX) THEN
      DO 40 J = 1, M
         READ (NIN, *) (X(I*M+J), I=0, N-1)
40
      CONTINUE
      WRITE (NOUT, *)
      WRITE (NOUT,*) 'Original data values'
      WRITE (NOUT, *)
      DO 60 J = 1, M
         WRITE (NOUT, 99999) (X(I*M+J), I=0, N-1)
60
      CONTINUE
      IFAIL = 0
       Compute transform
      CALL CO6RCF('Forward',M,N,X,WORK,IFAIL)
```

[NP3546/20A] C06RCF.3

```
WRITE (NOUT, *)
         WRITE (NOUT,*) 'Discrete quarter-wave Fourier sine transforms'
         WRITE (NOUT, *)
         DO 80 J = 1, M
            WRITE (NOUT, 99999) (X(I*M+J), I=0, N-1)
   80
        CONTINUE
         Compute inverse transform
         CALL CO6RCF('Backward',M,N,X,WORK,IFAIL)
         WRITE (NOUT, *)
         WRITE (NOUT,*) 'Original data as restored by inverse transform'
         WRITE (NOUT, *)
         DO 100 J = 1, M
            WRITE (NOUT, 99999) (X(I*M+J), I=0, N-1)
 100
         CONTINUE
         GO TO 20
      ELSE
        WRITE (NOUT,*) 'Invalid value of M or N'
      END IF
 120 CONTINUE
      STOP
99999 FORMAT (6X,7F10.4)
      END
```

9.2 Program Data

```
C06RCF Example Program Data
3 6: Number of sequences, M, and number of values in each sequence, N
0.3854 0.6772 0.1138 0.6751 0.6362 0.1424 : X, sequence 1
0.5417 0.2983 0.1181 0.7255 0.8638 0.8723 : X, sequence 2
0.9172 0.0644 0.6037 0.6430 0.0428 0.4815 : X, sequence 3
```

9.3 Program Results

COGRCF Example Program Results

Original data values

	0.3854 0.5417 0.9172	0.6772 0.2983 0.0644	0.1138 0.1181 0.6037	0.6751 0.7255 0.6430	0.6362 0.8638 0.0428	0.1424 0.8723 0.4815
Discrete quarter-wave Fourier sine transforms						
	0.7304	0.2078	0.1150	0.2577	-0.2869	-0.0815

 0.9274
 -0.1152
 0.2532
 0.2883
 -0.0026
 -0.0635

 0.6268
 0.3547
 0.0760
 0.3078
 0.4987
 -0.0507

Original data as restored by inverse transform

```
0.3854
         0.6772
                  0.1138
                                      0.6362
                          0.6751
                                              0.1424
0.5417
         0.2983
                   0.1181
                            0.7255
                                      0.8638
                                               0.8723
0.9172
         0.0644
                   0.6037
                            0.6430
                                      0.0428
                                                0.4815
```

C06RCF.4 (last) [NP3546/20A]